

Nano Mechanisms - NPS-XY-100A

Specification

Parameter	Symbol	Value			Units	Comments
Static Physical						
		Minimum	Typical	Maximum		
Material		Super Invar (Bright Nickel Plated)				
Size		100 x 100 x 23			mm	Note 1
*Range	$d_{sp,max}$	50	55		μm	
*Scale factor	b_{x1}		1		μm	Note 2
Scale factor error (1σ)	δb_{x1}			0.1	%	
Static Stiffness	k_x		1		$\text{N}\cdot\mu\text{m}^{-1}$	
Resonant frequency : 0g load	f_{0-0}		350		Hz	
50g load	f_{0-50}		260		Hz	
1000g load	f_{0-1000}		120		Hz	
Maximum load				1	Kg	Note 3
Dynamic Physical (Typical Values)						
Loop Setting:		Fast	Medium	Slow		Note 4
Bandwidth	$B_{x,p}$	53	20	4	Hz	
*Small signal settle time	$t_{s,s}$	15	30	130	Ms	Note 5
*Position noise (1σ)	$\delta X_{p,n}$	0.7	0.5	0.25	Nm	Note 6
Slew rate	$u_{sp,max}$	3	2	0.5	$\mu\text{m}\cdot\text{ms}^{-1}$	Note 7
Error Terms						
		Minimum	Typical	Maximum		
*Hysteresis (peak to peak)	$\delta X_{p,hyst}$		0.005	0.01	%	Note 8
*Linearity error (peak)	$\delta X_{p,lin}$		0.01	0.02	%	Note 9
*Rotational error	$\delta\phi$		10	25	μrad	Note 10
*Rotational error	$\delta\theta$		5	10	μrad	Note 10
*Rotational error	$\delta\gamma$		5	10	μrad	Note 10
Orthogonality	$\delta\phi_{orth}$		8		mrad	

*These parameters are measured and supplied with each mechanism.

1. With 40 mm diameter central aperture.
2. All position commands are given in micrometers with 7 digit resolution.
3. Depends on orientation. 1 kg is the maximum load for gravity acting in the Z direction. 0.5 kg is the maximum load for gravity acting in the X or Y axes. Loads greater than 5 kg can cause damage to the flexure mechanism.
4. For dynamic operation the servo loop parameters are preset for different performances; the parameters are user settable via software control. Fast means the fastest the stage can stably move with less than 50 grams load. Medium means the maximum speed for loads up to 200 grams. Slow means the speed at which the servo loop is stable for all masses up to the maximum allowed mass - equivalently low noise setting.
5. This is the 2% settle time. It is a function of the servo loop parameters which are user controllable. The test step size is 500nm.
6. The actual position noise of the stage.
7. The highest rate of change of true position with time that can be achieved. It is limited by the closed loop parameters; the absolute maximum value is (in open loop operation) $\sim 10 \mu\text{m}\cdot\text{ms}^{-1}$.
8. Percent of the displacement. The hysteresis specification for a displacement of less than 1 μm amplitude is 0.1 nm.
9. Percent error over the full range of motion.
10. Angular motion over the full range of the stage. These rotational errors are rotational errors around the Z, Y, and X axes respectively